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ON THE GENERALIZED F-SUZUKI-CONTRACTIONS

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ABSTRACT. In this paper, we introduce the new notion of generalized F -Suzuki-contraction in the setup of dislocated S_b -metric spaces. We establish some fixed point theorems involving this contraction in complete dislocated S_b -metric spaces. We also furnish an example to verify the effectiveness and applicability of our results.

1. INTRODUCTION

In 2012, Sedghi et al. [5] introduced the concept of S -metric space by modifying D -metric and G -metric spaces and proved some fixed point theorems for a self-mapping on a complete S -metric space. After that Özgür and Taş studied some generalizations of the Banach contraction principle on S -metric spaces. Sedghi et al. [4] introduced the concept of S_b -metric space as a generalization of S -metric space and proved some coupled common fixed point theorems in S_b -metric space .

On the other hand, Wardowski [6] introduced a new contraction, the so-called F -contraction, and obtained a fixed point result as a generalization of the Banach contraction principle. Thereafter, Dung and Hang studied the notion of a generalized F -contraction and established certain fixed point theorems for such mappings. Recently, Piri and Kumam [2] extended the fixed point results of [6] by introducing a generalized F -Suzuki-contraction in b -metric spaces.

Motivated by the aforementioned works, in this paper, we introduce the new notion of generalized F -Suzuki-contraction in the setup of dislocated S_b -metric spaces. We establish some fixed point theorems involving this contraction in complete dislocated S_b -metric spaces. We also furnish an example to verify the effectiveness and applicability of our results.

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We begin with some basic well-known definitions and results which will be used further on. Throughout this paper \mathbb{R} , \mathbb{R}_+ , \mathbb{N} denote the set of all real numbers, the set of all nonnegative real numbers and the set of all positive integers, respectively.

Definition 1.1. [5] Let X be a nonempty set. An S -metric on X is a function $S : X^3 \rightarrow \mathbb{R}_+$ that satisfies the following conditions:

- (S1) $0 < S(x, y, z)$ for each $x, y, z \in X$ with $x \neq y \neq z \neq x$,
- (S2) $S(x, y, z) = 0$ if and only if $x = y = z$,
- (S3) $S(x, y, z) \leq S(x, x, a) + S(y, y, a) + S(z, z, a)$ for each $x, y, z, a \in X$.

Then the pair (X, S) is called an S -metric space.

Definition 1.2. [4] Let X be a nonempty set and $b \geq 1$ be a given real number. Suppose that a mapping $S_b : X^3 \rightarrow \mathbb{R}_+$ satisfies:

- (S_b 1) $0 < S_b(x, y, z)$ for all $x, y, z \in X$ with $x \neq y \neq z \neq x$,
- (S_b 2) $S_b(x, y, z) = 0$ if and only if $x = y = z$,
- (S_b 3) $S_b(x, y, z) \leq b(S_b(x, x, a) + S_b(y, y, a) + S_b(z, z, a))$ for all $x, y, z, a \in X$.

Then S_b is called an S_b -metric on X and the pair (X, S_b) is called an S_b -metric space.

Definition 1.3. [4] If (X, S_b) is an S_b -metric space, a sequence $\{x_n\}$ in X is said to be:

- (1) Cauchy sequence if, for each $\varepsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that $S_b(x_n, x_n, x_m) < \varepsilon$ for all $m, n \geq n_0$.
- (2) convergent to a point $x \in X$ if, for each $\varepsilon > 0$, there exists a positive integer n_0 such that $S_b(x_n, x_n, x) < \varepsilon$ or $S_b(x, x, x_n) < \varepsilon$ for all $n \geq n_0$, and we denote by $\lim_{n \rightarrow \infty} x_n = x$.

Definition 1.4. [4] An S_b -metric space (X, S_b) is called complete if every Cauchy sequence is convergent in X .

Example 1.5. [3] Let $X = \mathbb{R}$. Define $S_b : X^3 \rightarrow \mathbb{R}_+$ by $S_b(x, y, z) = |x - z| + |y - z|$ for all $x, y, z \in X$. Then (X, S_b) is a complete S_b -metric space with $b = 2$.

Definition 1.6. [6] Let \mathcal{F} be the family of all functions $F : (0, +\infty) \rightarrow \mathbb{R}$ such that:

- (F1) F is strictly increasing, that is for all $\alpha, \beta \in (0, +\infty)$ such that $\alpha < \beta$, $F(\alpha) < F(\beta)$,
- (F2) for each sequence $\{\alpha_n\}$ of positive numbers, $\lim_{n \rightarrow +\infty} \alpha_n = 0$ if and only if $\lim_{n \rightarrow +\infty} F(\alpha_n) = -\infty$,
- (F3) there exists $k \in (0, 1)$ such that $\lim_{\alpha \rightarrow 0^+} \alpha^k F(\alpha) = 0$.

In 2014, Piri and Kumam described a large class of functions by replacing the condition (F3) in the above definition with the following one:

- (F3') F is continuous on $(0, +\infty)$.

They denote by \mathfrak{F} the family of all functions $F : (0, +\infty) \rightarrow \mathbb{R}$ which satisfy conditions (F1), (F2), and (F3').

We use \mathfrak{F}_G to denote the set of all functions $F : (0, +\infty) \rightarrow \mathbb{R}$ which satisfy conditions (F1) and (F3') and Ψ to denote the set of all functions $\psi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ such that ψ is continuous and $\psi(t) = 0$ if and only if $t = 0$ (see [2]).

Definition 1.7. [2] Let (X, d) be a b -metric space. A self-mapping $T : X \rightarrow X$ is said to be a generalized F -Suzuki-contraction if there exists $F \in \mathfrak{F}_G$ such that, for all $x, y \in X$ with $x \neq y$,

$$\frac{1}{2s}d(x, Tx) < d(x, y) \Rightarrow F(s^5d(Tx, Ty)) \leq F(M_T(x, y)) - \psi(M_T(x, y)),$$

in which $\psi \in \Psi$ and

$$M_T(x, y) = \max \left\{ d(x, y), d(T^2x, y), \frac{d(Tx, y) + d(x, Ty)}{2s}, \frac{d(T^2x, x) + d(T^2x, Ty)}{2s}, \right. \\ \left. d(T^2x, Ty) + d(T^2x, Tx), d(T^2x, Ty) + d(Tx, x), d(Tx, y) + d(y, Ty) \right\}.$$

Theorem 1.8. [2] Let (X, d) be a complete b -metric space and $T : X \rightarrow X$ be a generalized F -Suzuki-contraction. Then T has a unique fixed point $x^* \in X$ and for every $x \in X$ the sequence $\{T^n x\}$ converges to x^* .

2. MAIN RESULTS

In this section, we first introduce the concept of dislocated S_b -metric space and then we demonstrate a fixed point result for generalized F -Suzuki-contractions in such spaces.

Definition 2.1. [1] Let X be a nonempty set and $b \geq 1$ be a given real number. A mapping $S_b : X^3 \rightarrow \mathbb{R}_+$ is a dislocated S_b -metric if, for all $x, y, z, a \in X$, the following conditions are satisfied:

- (dS_b1) $S_b(x, y, z) = 0$ implies $x = y = z$,
- (dS_b2) $S_b(x, y, z) \leq b(S_b(x, x, a) + S_b(y, y, a) + S_b(z, z, a))$.

A dislocated S_b -metric space is a pair (X, S_b) such that X is a nonempty set and S_b is a dislocated S_b -metric on X . In the case that $b = 1$, S_b is denoted by S and it is called dislocated S -metric, and the pair (X, S) is called dislocated S -metric space.

Definition 2.2. [1] Let (X, S_b) be a dislocated S_b -metric space, $\{x_n\}$ be any sequence in X and $x \in X$. Then:

- (i) The sequence $\{x_n\}$ is said to be a Cauchy sequence in (X, S_b) if, for each $\varepsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that $S_b(x_n, x_n, x_m) < \varepsilon$ for each $m, n \geq n_0$.
- (ii) The sequence $\{x_n\}$ is said to be convergent to x if, for each $\varepsilon > 0$, there exists a positive integer n_0 such that $S_b(x, x, x_n) < \varepsilon$ for all $n \geq n_0$ and we denote it by $\lim_{n \rightarrow \infty} x_n = x$.
- (iii) (X, S_b) is said to be complete if every Cauchy sequence is convergent.

The following example shows that a dislocated S_b -metric need not be a dislocated S -metric.

Example 2.3. [1] Let $X = \mathbb{R}_+$, then the mapping $S_b : X^3 \rightarrow \mathbb{R}_+$ defined by $S_b(x, y, z) = x + y + 4z$ is a complete dislocated S_b -metric on X with $b = 2$. However, it is not a dislocated S -metric space. Indeed, we have

$$4 = S_b(0, 0, 1) \not\leq 2S_b(0, 0, 0) + S_b(1, 1, 0) = 2.$$

Definition 2.4. [1] Let (X, S_b) be a dislocated S_b -metric space. A mapping $T : X \rightarrow X$ is said to be a generalized F -Suzuki-contraction if there exists $F \in \mathfrak{F}$ such that for all $x, y \in X$

$$\frac{1}{2b} S_b(x, x, Tx) < S_b(x, x, y) \Rightarrow F(2b^3 S_b(Tx, Tx, Ty)) \leq F(M_T(x, y)) - \psi(M_T(x, y)), \quad (2.1)$$

where $\psi \in \Psi$ and

$$M_T(x, y) = \max \left\{ S_b(x, x, y), \frac{S_b(y, y, Ty)}{10}, \frac{S_b(x, x, Tx)}{10}, S_b(Tx, Tx, Ty), \right. \\ \left. \frac{S_b(y, y, Tx)}{18b}, \frac{S_b(Tx, Tx, T^2x)}{2} \right\}.$$

Our main result is the following.

Theorem 2.5. [1] Let (X, S_b) be a complete dislocated S_b -metric space and $T : X \rightarrow X$ be a generalized F -Suzuki-contraction satisfying the following condition:

$$\max \left\{ \frac{S_b(y, y, Ty)}{10}, \frac{S_b(x, x, Tx)}{10}, \frac{S_b(y, y, Ty)}{9} + \frac{S_b(Tx, Tx, Ty)}{18}, \frac{S_b(Tx, Tx, T^2x)}{2} \right\} \leq S_b(Tx, Tx, Ty)$$

for all x, y in X . Then T has a unique fixed point in X .

Example 2.6. [1] Let $X = \{-1, 0, 1\}$. Define the mapping $S_b : X^3 \rightarrow \mathbb{R}_+$ by

$$S_b(x, y, z) = \begin{cases} \frac{3}{2}, & 0 = x = y \neq z = 1 \text{ or } -1 = x = y \neq z = 1 \\ \frac{10}{6}, & 1 = x = y \neq z \\ 0, & x = y = z = -1 \text{ or } 1 \\ \frac{1}{5}, & \text{otherwise} \end{cases}$$

for all $x, y, z \in X$. Therefore (X, S_b) is a complete dislocated S_b -metric space with $b = \frac{3}{2}$. Put $F(\alpha) = \ln \alpha$ ($\alpha > 0$) and $\psi(t) = t$ ($t \geq 0$). Define $T : X \rightarrow X$ by

$$T(x) = \begin{cases} 0, & x = 1 \\ -1, & x = -1, 0. \end{cases}$$

Hence, T is a generalized F -Suzuki-contraction which satisfies the assumption of Theorem 2.5 and so it has a unique fixed point -1 .

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